

Elastic Turbulence in Flatland: A Tale of Blobs, Barriers, and Inhomogeneous Mixing

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Outline

- Elastic Fluids:

Elasticity \Leftrightarrow Memory \Leftrightarrow Transport

- Active Scalar Transport in 2D MHD:

Conventional Wisdom

- New Development: Blobs and Barriers
- Revisiting Quenching
- Inhomogeneous Mixing and Staircases
- Open Questions

Elastic Fluids

- Internal DOF exerting restoring force on fluid → “springiness”
- Examples:
 - MHD → $\vec{B}, \vec{j} \times \vec{B}$
 - Polymer hydro → Elastic element oldroyd-B
 - Spinodal Decomposition (CHNS) → droplet surface tension
- Elasticity → Memory → Impact on mixing?!



Active Scalar Transport

in 2D MHD:

Background and

Conventional Wisdom

Physics: Active Scalar Transport

- Magnetic diffusion, A transport are cases of active scalar transport
- (Focus: 2D MHD) (Cattaneo, Vainshtein '92, Gruzinov, P. D. '94, '95)

scalar mixing – the usual

$$\partial_t A + \nabla \phi \times \hat{z} \cdot \nabla A = \eta \nabla^2 A$$

$$\partial_t \nabla^2 \phi + \nabla \phi \times \hat{z} \cdot \nabla \nabla^2 \phi = \nabla A \times \hat{z} \cdot \nabla \nabla^2 A + \nu \nabla^2 \nabla^2 \phi + \tilde{f}$$

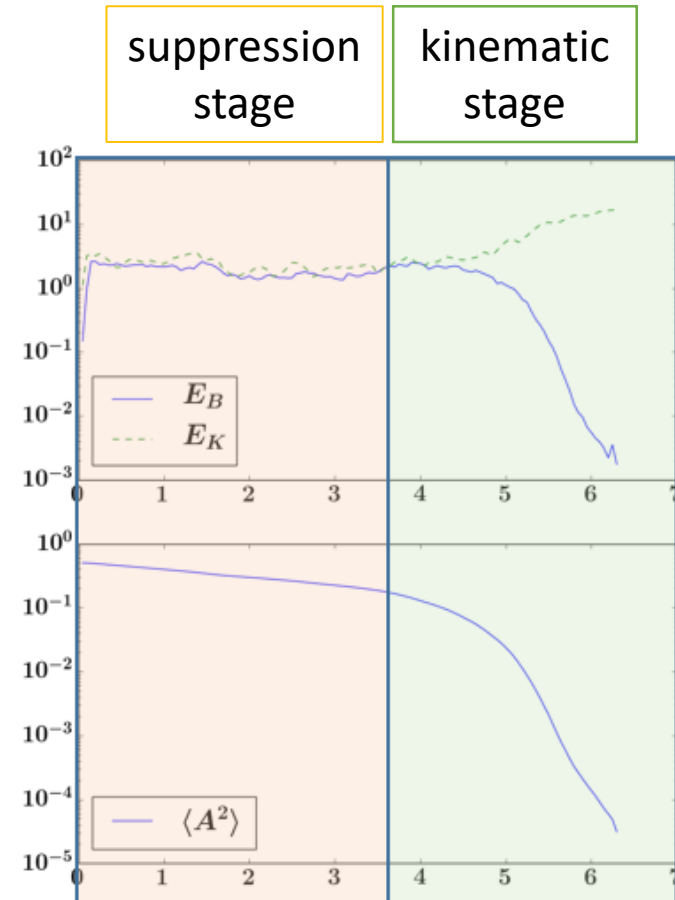
turbulent resistivity

back-reaction

- Seek $\langle v_x A \rangle = -D_T \frac{\partial \langle A \rangle}{\partial x} - \eta \frac{\partial \langle A \rangle}{\partial x}$
- Point: $D_T \neq \sum_{\vec{k}} |v_{\vec{k}}|^2 \tau_{\vec{k}}^K$, often substantially less than kinematic
- Why: Memory! \leftrightarrow Freezing-in
- Cross Phase

Two Stage Evolution:

- 1. The suppression stage: the (large scale) magnetic field is sufficiently strong so that the diffusion is suppressed.
- 2. The kinematic decay stage: the magnetic field is dissipated so the diffusion rate returns to the kinematic rate.
- Suppression is due to the memory induced by the magnetic field.



Conventional Wisdom

- [Cattaneo and Vainshtein 1991]: turbulent transport is suppressed, even for a weak large scale magnetic field is present.

- Starting point: $\partial_t \langle A^2 \rangle = -2\eta \langle B^2 \rangle$

- Assumptions:

- Energy equipartition: $\frac{1}{\mu_0 \rho} \langle B^2 \rangle \sim \langle v^2 \rangle$

- Average B can be estimated by: $|\langle \mathbf{B} \rangle| \sim \sqrt{\langle A^2 \rangle} / L_0$

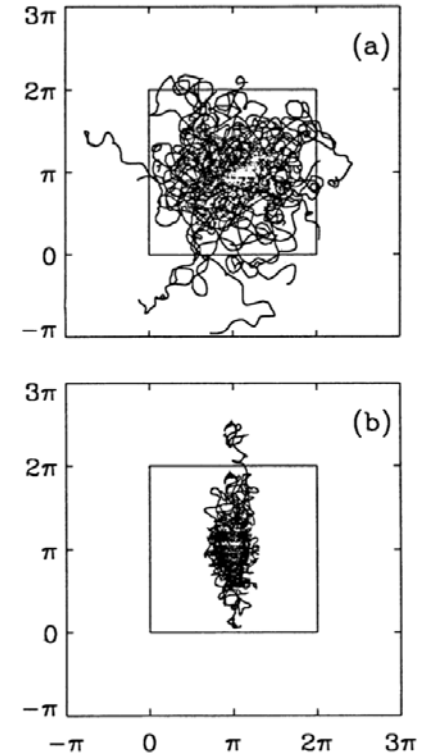
- Define Mach number as: $M^2 = \langle v_A \rangle^2 / \langle \tilde{v}^2 \rangle = \langle v^2 \rangle / v_A^2 = \langle v^2 \rangle / \frac{1}{\mu_0 \rho} \langle B^2 \rangle$

- Result for suppression stage: $\eta_T \sim \eta M^2$

- Fit together with kinematic stage result:

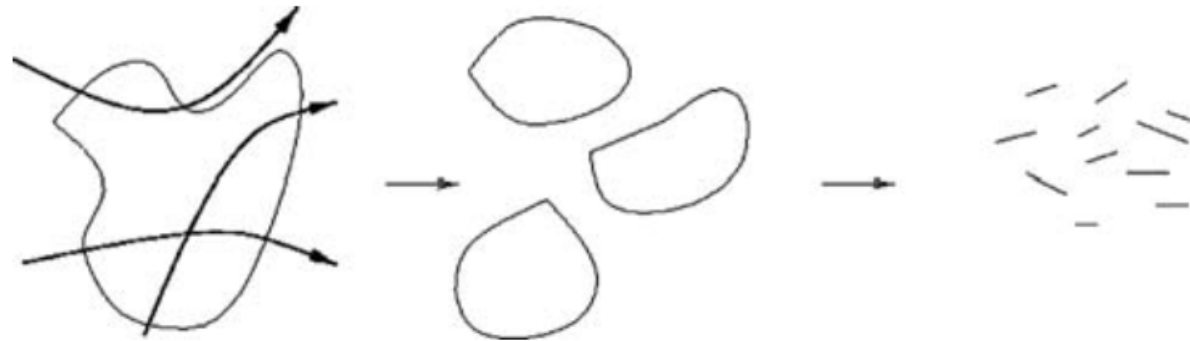
$$\eta_T \sim \frac{ul}{1 + \text{Rm}/M^2}$$

- Physics interpretation of η_T ?



Origin of Memory?

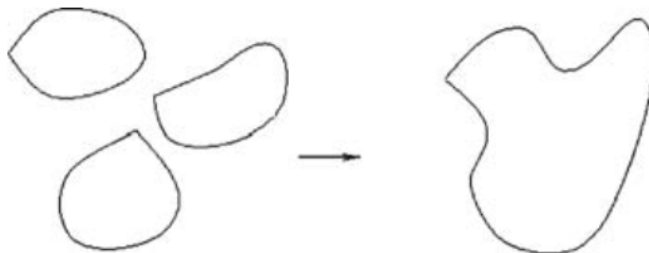
- (a) flux advection vs flux coalescence
 - intrinsic to 2D MHD (and CHNS)
 - rooted in inverse cascade of $\langle A^2 \rangle$ - dual cascades
- (b) tendency of (even weak) mean magnetic field to “Alfvenize” turbulence [cf: vortex disruption feedback threshold!]
- Re (a): Basic physics of 2D MHD



Forward transfer: fluid eddies chop up scalar A .

Memory Cont'd

- V.S.



Inverse transfer: current filaments and A-blobs attract and coagulate.

- Obvious analogy: straining vs coalescence
- Upshot: closure calculation yields:

$$\Gamma_A = - \sum_{\vec{k}'} [\tau_c^\phi \langle v^2 \rangle_{\vec{k}'} - \tau_c^A \langle B^2 \rangle_{\vec{k}'}] \frac{\partial \langle A \rangle}{\partial x} + \dots$$

flux of potential

competition

scalar advection vs. coalescence (“negative resistivity”)

(+)

(-)

N.B.:

Coalescence

→ Negative diffusion

→ Bifurcation

Conventional Wisdom, Cont'd

- Then calculate $\langle B^2 \rangle$ in terms of $\langle v^2 \rangle$ (after Zeldovich)

$$\partial_t A + \mathbf{v} \cdot \nabla A = -v_x \frac{\partial \langle A \rangle}{\partial x} + \eta \nabla^2 A$$

- Multiplying by A and sum over modes:

$$\frac{1}{2} [\cancel{\partial_t \langle A^2 \rangle} + \cancel{\langle \nabla \cdot (\mathbf{v} A^2) \rangle}] = -\Gamma_A \frac{\partial \langle A \rangle}{\partial x} - \eta \langle B^2 \rangle \quad \frac{\partial \langle A \rangle}{\partial x} \rightarrow B_0$$

Dropped stationary case

Dropped periodic boundary \rightarrow introduce nonlocality?!

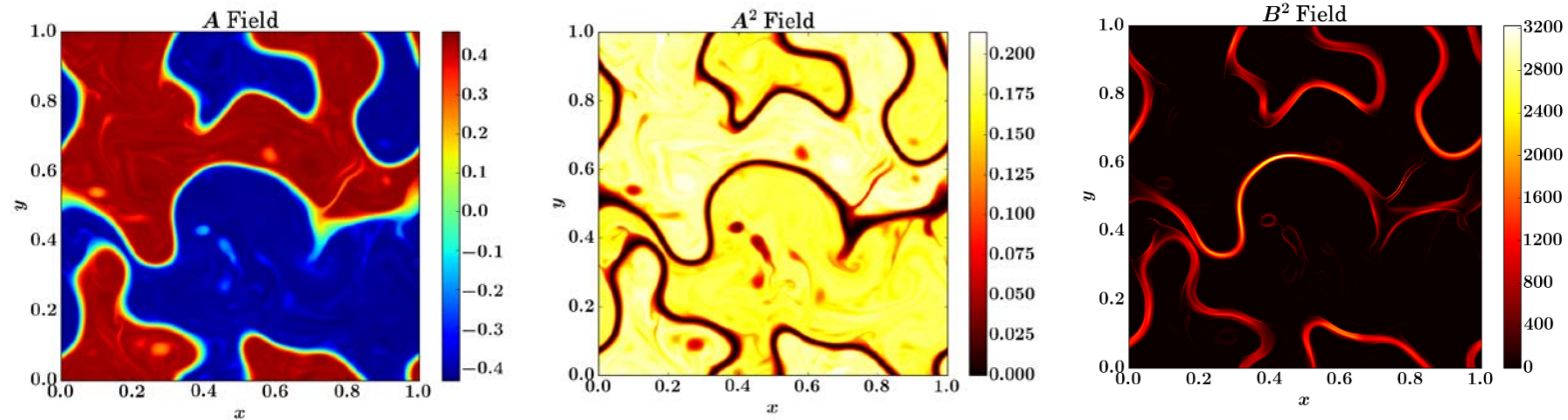
- Therefore: $\langle B^2 \rangle = -\frac{\Gamma_A}{\eta} \frac{\partial \langle A \rangle}{\partial x} = \frac{\eta_T}{\eta} B_0^2$
- Define Mach number as: $M^2 \equiv \langle v^2 \rangle / v_{A0}^2 = \langle v^2 \rangle / (\frac{1}{\mu_0 \rho} B_0^2)$
- Result: $\eta_T = \frac{\sum_{\mathbf{k}} \tau_c \langle v^2 \rangle_{\mathbf{k}}}{1 + \text{Rm}/M^2} = \frac{ul}{1 + \text{Rm}/M^2}$
- This theory is not able to describe $B_0 \rightarrow 0$ limited!

New Wrinkles

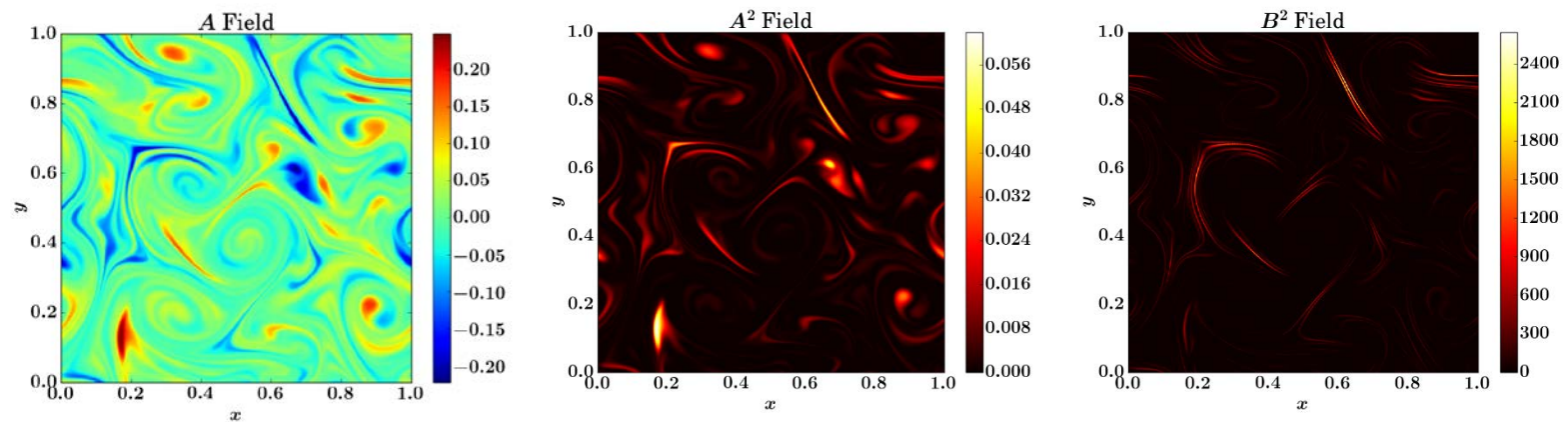
New Observations

Field

- With no imposed B_0 , in suppression stage: Concentrated!



- v.s. same run, in kinematic stage (trivial):

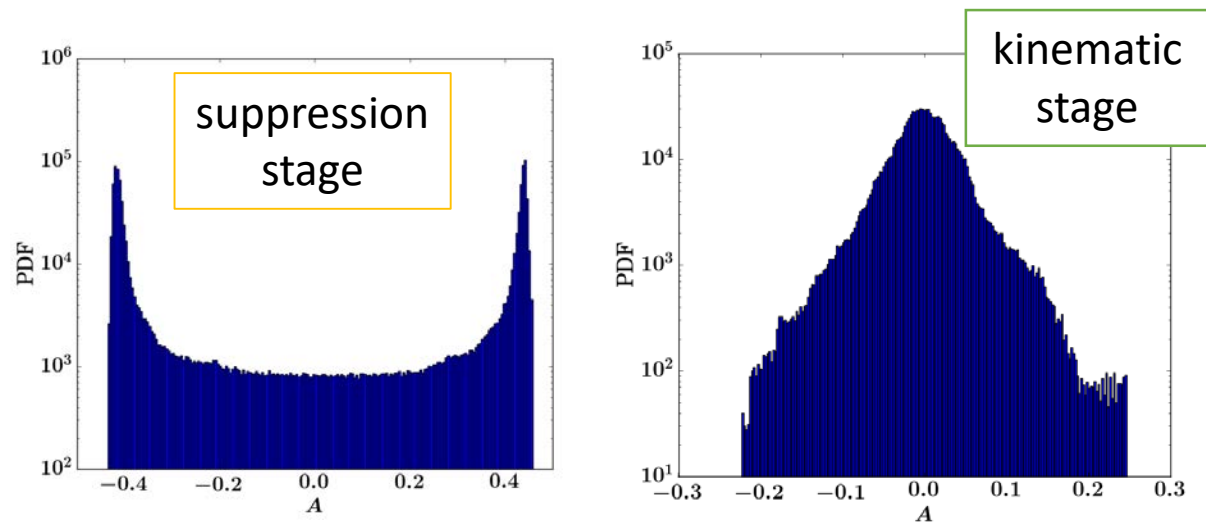


New Observations Cont'd

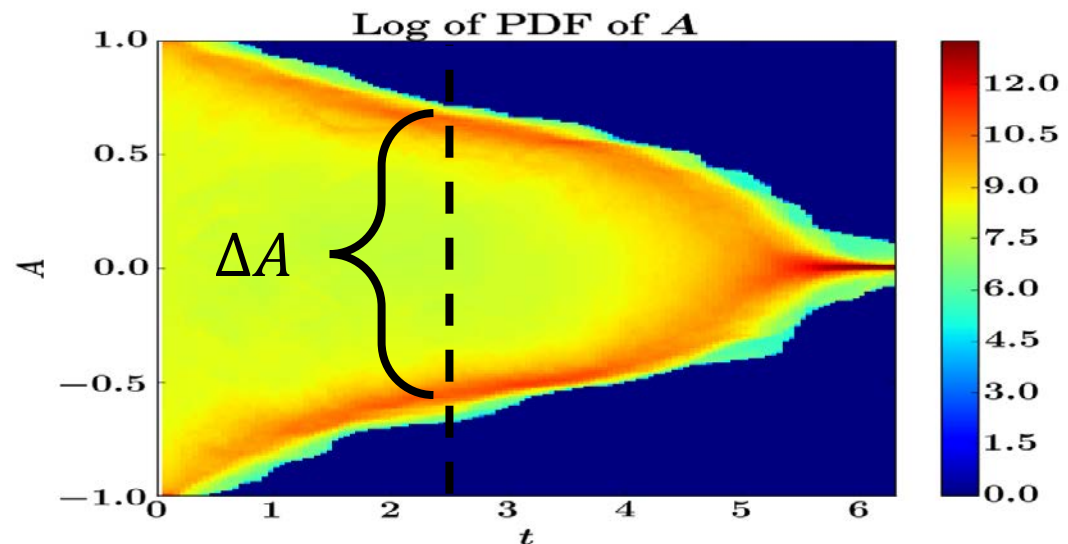
- Nontrivial structure formed in real space during the suppression stage.
 - A field is evidently composed of “blobs”.
 - The low A^2 regions \leftrightarrow 1-dimensional.
 - The high B^2 regions are strongly correlated with low A^2 regions, and also \leftrightarrow 1-dimensional.
 - 1-dimensional high B^2 regions “barriers”. There, mixing is sharply reduced, relative to η_K .
- ➔ Story one of ‘blobs and barriers’

Evolution of PDF of A

- Probability Density Function (PDF) in two stage:

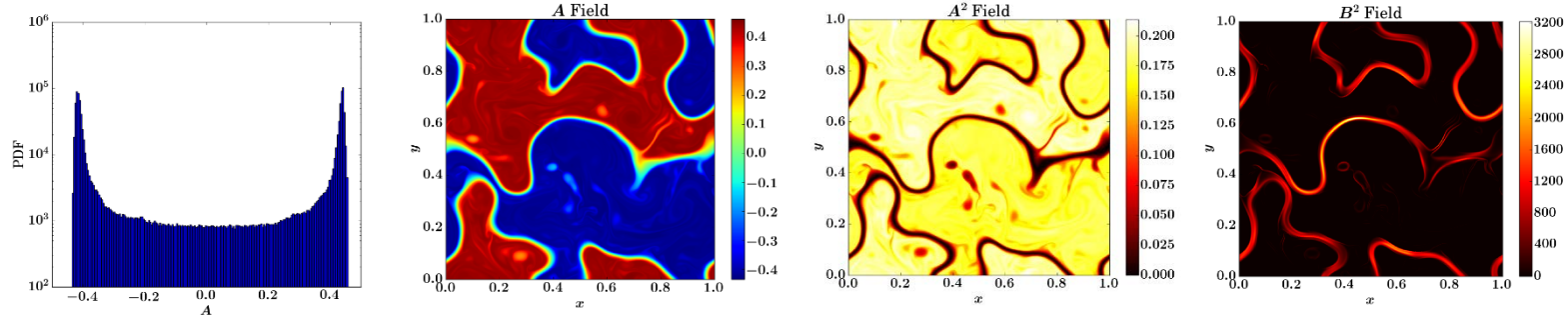


- Time evolution: horizontal "Y".
- The PDF changes from double peak to single peak as the system evolves from the suppression stage to the kinematic stage.



Unimodal Initial Condition

- One may question whether the bimodal PDF feature is purely due to the initial condition. The answer is No.
- Two non-zero peaks in PDF of A still arise, even if the initial condition is unimodal.

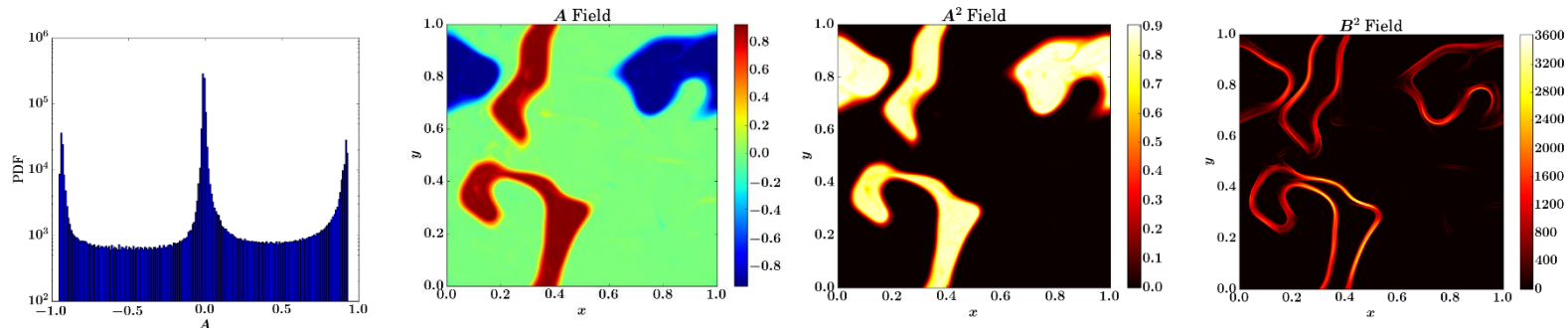


(a1)

(a2)

(a3)

(a4)



(b1)

(b2)

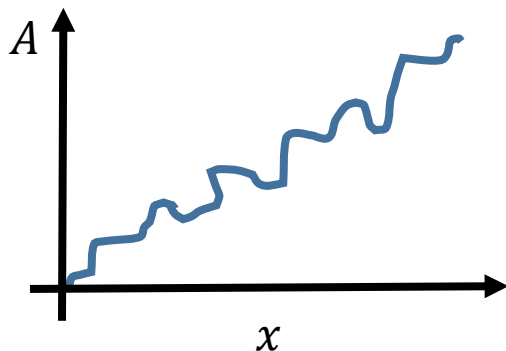
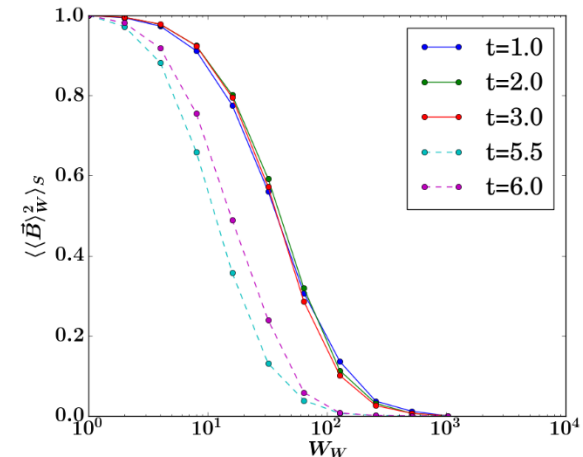
(b3)

(b4)

The problem of the mean field $\langle B \rangle$

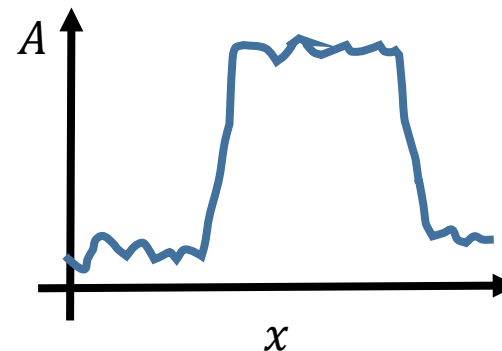
→ What does “Mean” mean?

- $\langle B \rangle$ depends on the averaging window.
- With no imposed external field, B is highly intermittent, therefore $\langle B \rangle$ is not well defined.



$$|\langle B \rangle| \sim \sqrt{\langle A^2 \rangle} / L_0 \quad \checkmark$$

v.s.



$\langle B \rangle$ not well defined

Reality

Revisiting Quenching

New Understanding

- Summary of important length scales: $l < L_{stir} < L_{env} < L_0$
 - System size L_0
 - Envelope size $L_{env} \rightarrow$ emergent (blob)
 - Stirring length scale L_{stir}
 - Turbulence length scale l , here we use Taylor microscale λ
 - Barrier width $W \rightarrow$ emergent
- Quench is not uniform. Transport coefficients differ in different regions.
- In the regions where magnetic fields are strong, Rm/M^2 is dominant. They are regions of **barriers**.
- In other regions, i.e. Inside blobs, Rm/M'^2 is what remains. $M'^2 \equiv \langle V^2 \rangle / \left(\frac{1}{\rho} \langle A^2 \rangle / L_{env}^2 \right)$

New Understanding, cont'd

- From $\partial_t \langle A^2 \rangle = -\langle \mathbf{v}A \rangle \cdot \nabla \langle A \rangle - \nabla \cdot \langle \mathbf{v}A^2 \rangle - \eta \langle B^2 \rangle$
- Retain 2nd term on RHS. Average taken over an envelope/blob scale.
- Define diffusion (closure):

$$\langle \mathbf{v}A \rangle = -\eta_{T1} \nabla \langle A \rangle$$

$$\langle \mathbf{v}A^2 \rangle = -\eta_{T2} \nabla \langle A^2 \rangle$$

- Plugging in: $\partial_t \langle A^2 \rangle = \eta_{T1} (\nabla \langle A \rangle)^2 + \nabla \eta_{T2} \cdot \nabla \langle A^2 \rangle - \eta \langle B^2 \rangle$
- For simplicity: $\langle B^2 \rangle \sim \frac{\eta_T}{\eta} (\langle B \rangle^2 + \langle A^2 \rangle / L_{env}^2)$
- L_{env} is the envelope size. Scale of variation of $\langle A^2 \rangle$.
- Define new strength parameter: $M'^2 \equiv \langle v^2 \rangle / (\frac{1}{\mu_0 \rho} \langle A^2 \rangle / L_{env}^2)$

- Result:

$$\eta_T = \frac{ul}{1 + \text{Rm}/M^2 + \text{Rm}/M'^2} = \frac{ul}{1 + \text{Rm} \frac{1}{\mu_0 \rho} \langle \mathbf{B} \rangle^2 / \langle v^2 \rangle + \text{Rm} \frac{1}{\mu_0 \rho} \langle A^2 \rangle / L_{env}^2 \langle v^2 \rangle}$$

$$\eta_T = V l / \left[1 + \frac{R_m}{M^2} + \frac{R_m}{M'^2} \right]$$

- Barriers:

$$\eta_T \approx V l / \left[1 + R_m \frac{\langle B \rangle^2}{\rho \langle \tilde{V}^2 \rangle} \right]$$

Strong field
↓

- Blobs:

$$\eta_T \approx V l / \left[1 + R_m \frac{\langle A^2 \rangle}{\rho L_{env}^2 \langle \tilde{V}^2 \rangle} \right]$$

Weak effective field
↓

- Quench stronger in barriers, highly non-uniform

Formation of Barriers

- How do the barriers form?

$$\eta_T = \sum_{\mathbf{k}} \tau_c [\langle v^2 \rangle_{\mathbf{k}} - \frac{1}{\mu_0 \rho} \langle B^2 \rangle_{\mathbf{k}}]$$

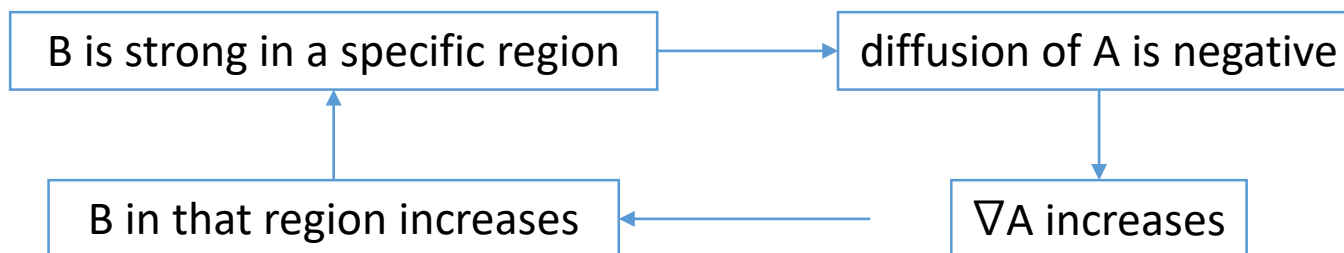
flux coalescence

- From above, strong B regions can support negative incremental

$$\eta_T = \delta \Gamma_A / \delta (-\nabla A) < 0, \text{ suggesting clustering}$$

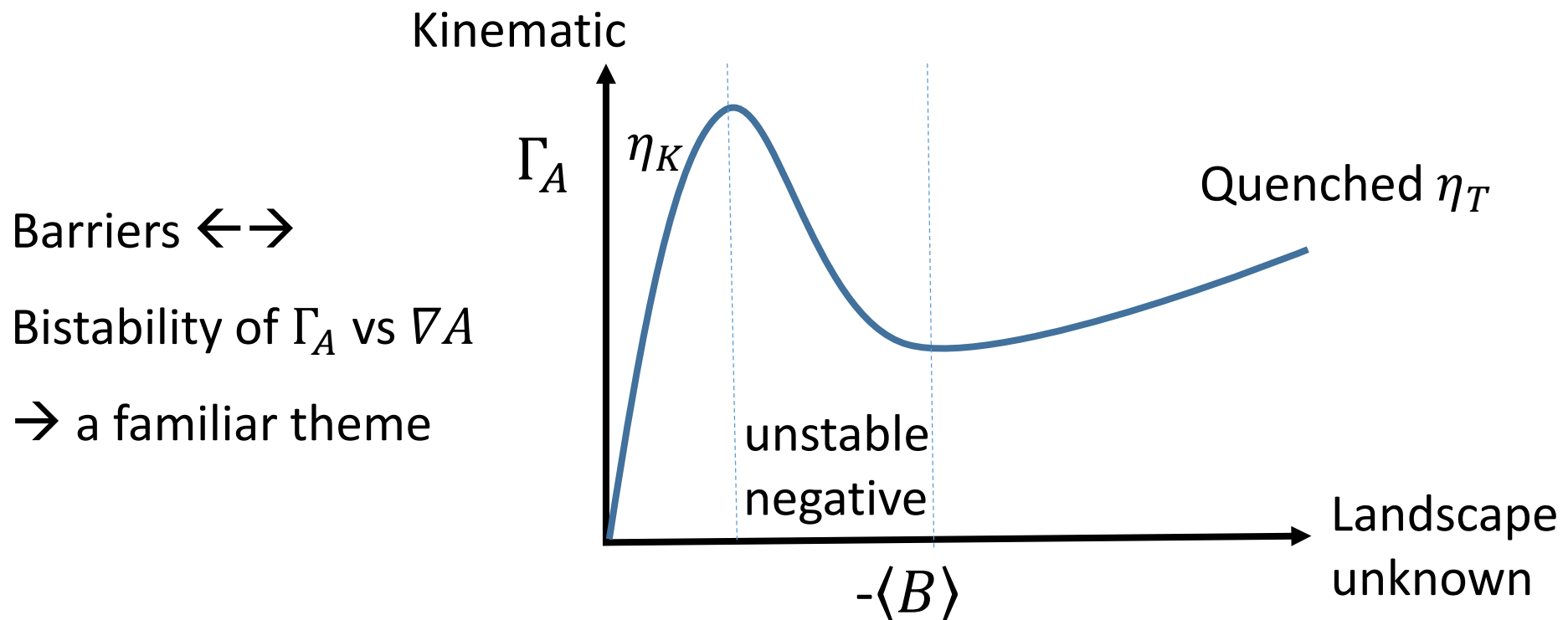
- $\langle \eta_T \rangle > 0$

- Positive feedback: a twist on a familiar theme



Formation of Barriers, Cont'd

- Negative resistivity leads to barrier formation.
- The S-curve due to the nonlinear dependence of Γ_A on B .
- When slope negative \rightarrow negative (incremental) resistivity.



Describing the Barriers

- How to measure the barrier width W .

- Starting point: $W \sim \Delta A / B_b$

- Use $\sqrt{\langle A^2 \rangle}$ to calculate ΔA

- Define the barrier regions as:

arbitrary threshold
↓

$$B(x, y) > \sqrt{\langle B^2 \rangle} * 2$$

- Define barrier packing fraction: $P \equiv \frac{\# \text{ of grid points for barrier regions}}{\# \text{ of total grid points}}$

- Use use the magnetic fields in the barrier regions to calculate the magnetic energy:

$$\sum_{\text{barriers}} B_b^2 \sim \sum_{\text{system}} B^2$$

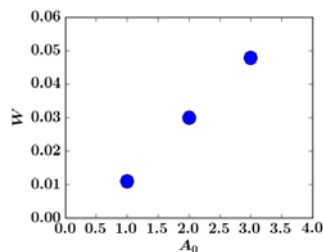
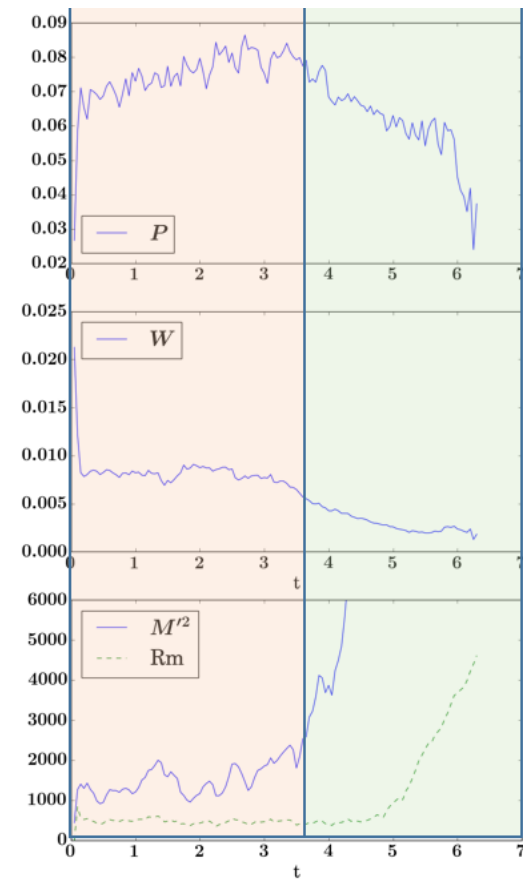
- Thus $\langle B_b^2 \rangle \sim \langle B^2 \rangle / P$

- So barrier width can be estimated by: $W^2 \equiv \langle A^2 \rangle / (\langle B^2 \rangle / P)$

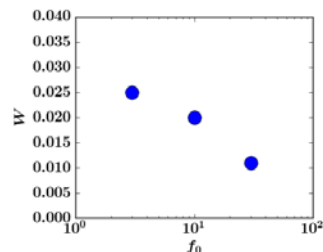
N.B. All magnetic energy in the barriers

Describing the Barriers

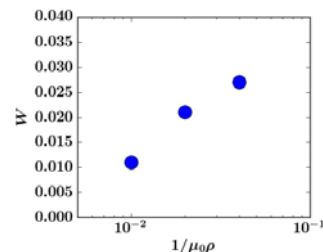
- Time evolution of P and W :
 - P , W collapse in decay
 - M' rises
- Sensitivity of W :
 - A_0 or $1/\mu_0\rho$ greater \rightarrow W greater;
 - f_0 greater, W smaller; (ala' Hinze)
 - W not sensitive to η or ν .



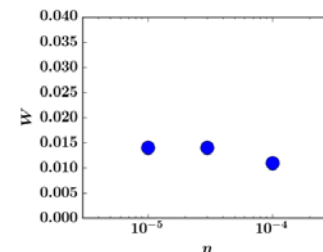
(a)



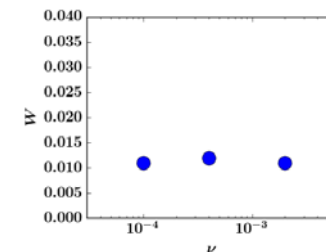
(b)



(c)



(d)

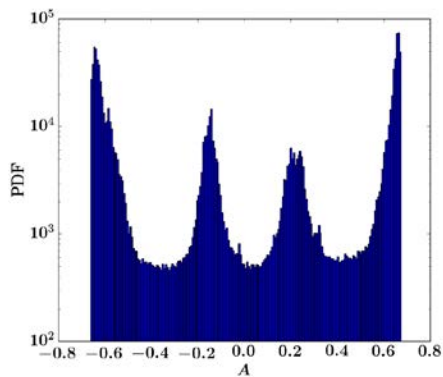


(e)

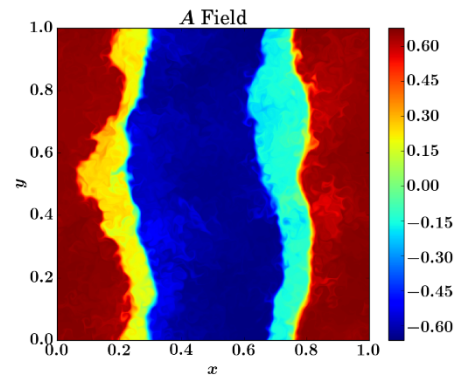
Active Scalar Staircases

Staircase (inhomogeneous Mixing, Bistability)

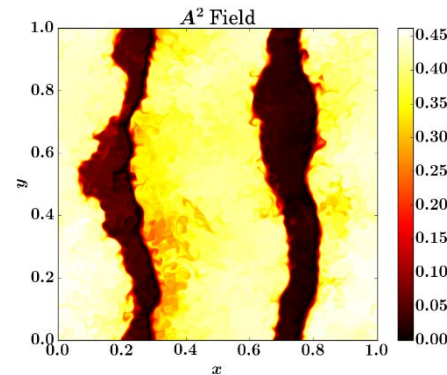
- Staircases emerge spontaneously! – Barrier lattices
- Initial condition is the usual cos function (bimodal)
- The only major sensitive parameter (from runs above) is the forcing scale $k=32$ (for all runs above $k=5$).
- Resembles the PV staircase



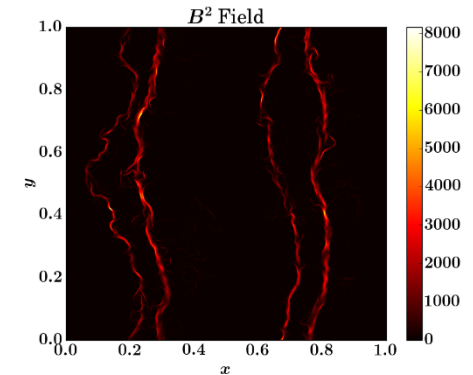
(1)



(2)



(3)



(4)

Conclusions / Summary

- Magnetic fields suppress turbulent diffusion in 2D MHD by: formation of intermittent **transport barriers**.
- Magnetic structures:
 - Barriers – thin, 1D strong field regions
 - Blobs – 2D, weak field regions
- Quench not uniform:

$$\eta_T = \frac{ul}{1 + \text{Rm} \frac{1}{\mu_0 \rho} \langle \mathbf{B} \rangle^2 / \langle v^2 \rangle + \text{Rm} \frac{1}{\mu_0 \rho} \langle A^2 \rangle / L_{env}^2 \langle v^2 \rangle}$$

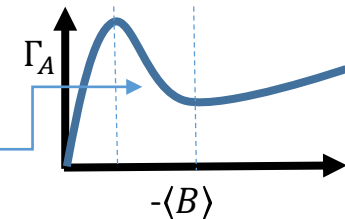
barriers, strong B

blobs, weak B, $\nabla^2 \langle A^2 \rangle$ remains

- Barriers form due to negative resistivity:

$$\eta_T = \sum_{\mathbf{k}} \tau_c [\langle v^2 \rangle_{\mathbf{k}} - \frac{1}{\mu_0 \rho} \langle B^2 \rangle_{\mathbf{k}}]$$

flux coalescence



- Formation of “magnetic staircases” observed for some stirring scale

General Conclusions (MHD and CHNS)

- Dual (or multiple) cascades can interact with each other, and can modify one another. N.B.: Focus on $\langle A^2 \rangle$ transfer.
- We show how a length scale, e.g. the Hinze scale in 2D CHNS, emerges from the balance of kinetic energy and elastic energy in blobby turbulence. \rightarrow blob scale in MHD?!
- Negative incremental resistivity can exist in a simple system such as 2D MHD. This results in the formation of nontrivial real space structure.

Future Works

- Extension of the transport study in MHD:
 - Numerical tests of the new η_T expression ?
 - What determines the barrier width and packing fraction ?
 - Why does layering appear when the forcing scale is small ?
 - What determines the step width, in the case of layering
- Other similar systems can also be studied in this spirit. e.g. Oldroyd-B model for polymer solutions. (drag reduction)
- Reduced Model of Magnetic Staircase

See Also:

C. Chen, P.D., Tobias: “PV Mixing in a Tangled Magnetic Field”, in preparation

Reading

Fan, P.D., Chacon:

- PRE Rap Comm 99, 041201 (2019)
- PoP 25, 055702 (2018)
- PRE Rap Comm 96, 041101 (2017)
- Phys Rev Fluids 1, 054403 (2016)

Thank you!

Back-Up

2D CHNS and 2D MHD

	2D MHD	2D CHNS
Magnetic Potential	A	ψ
Magnetic Field	\mathbf{B}	\mathbf{B}_ψ
Current	j	j_ψ
Diffusivity	η	D
Interaction strength	$\frac{1}{\mu_0}$	ξ^2

- 2D CHNS Equations:

$$\partial_t \psi + \vec{v} \cdot \nabla \psi = D \nabla^2 (-\psi + \psi^3 - \xi^2 \nabla^2 \psi)$$

$$\partial_t \omega + \vec{v} \cdot \nabla \omega = \frac{\xi^2}{\rho} \vec{B}_\psi \cdot \nabla \nabla^2 \psi + \nu \nabla^2 \omega$$

$-\psi$: Negative diffusion term

ψ^3 : Self nonlinear term

$-\xi^2 \nabla^2 \psi$: Hyper-diffusion term

With $\vec{v} = \hat{z} \times \nabla \phi$, $\omega = \nabla^2 \phi$, $\vec{B}_\psi = \hat{z} \times \nabla \psi$, $j_\psi = \xi^2 \nabla^2 \psi$. $\psi \in [-1, 1]$.

- 2D MHD Equations:

$$\partial_t A + \vec{v} \cdot \nabla A = \eta \nabla^2 A$$

$$\partial_t \omega + \vec{v} \cdot \nabla \omega = \frac{1}{\mu_0 \rho} \vec{B} \cdot \nabla \nabla^2 A + \nu \nabla^2 \omega$$

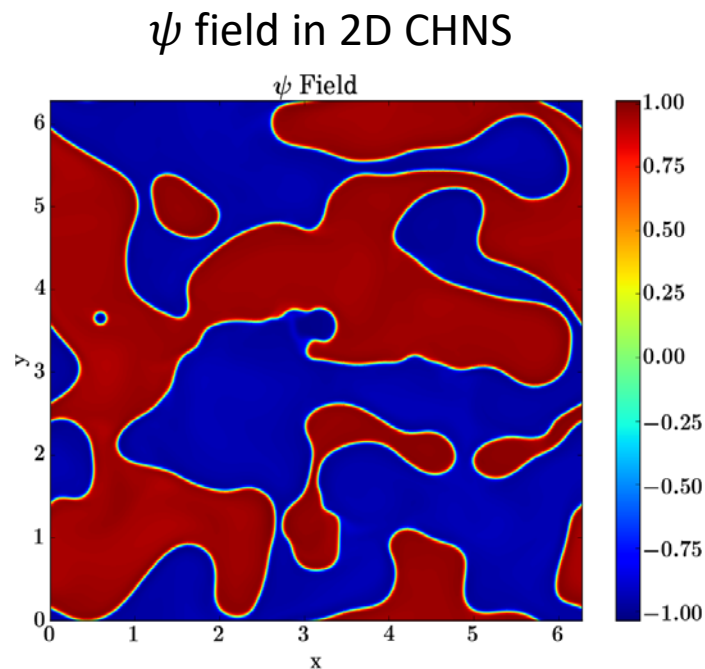
A : Simple diffusion term

See [Fan et.al. 2016] for more about CHNS.

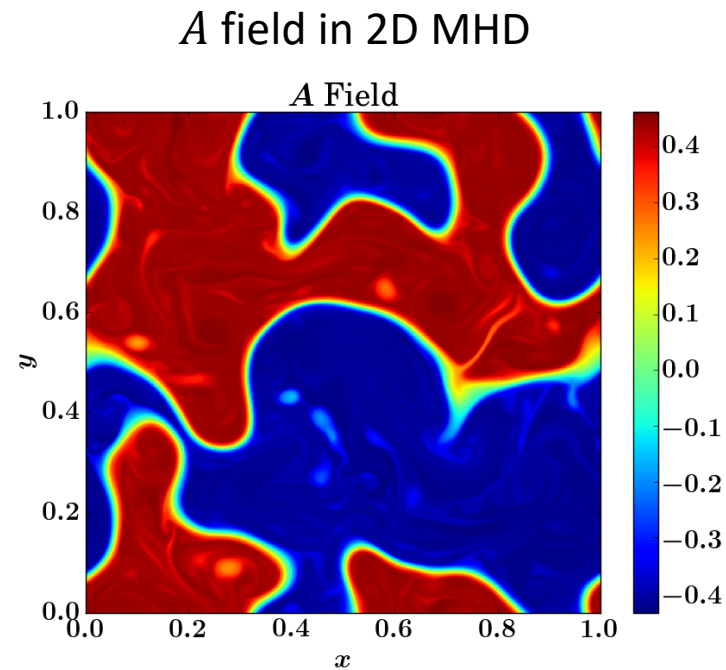
With $\vec{v} = \hat{z} \times \nabla \phi$, $\omega = \nabla^2 \phi$, $\vec{B} = \hat{z} \times \nabla A$, $j = \frac{1}{\mu_0} \nabla^2 A$

2D CHNS and 2D MHD

- The A field in 2D MHD in suppression stage is strikingly similar to the ψ field in 2D CHNS (Cahn-Hilliard Navier-Stokes) system:



V.S.



Constitutive Relations → Deborah Number

➤ J. C. Maxwell:

$$(\text{stress}) + \overset{\text{relaxation}}{\tau_R} \frac{d(\text{stress})}{dt} = \overset{\text{viscosity}}{\eta} \frac{d}{dt} (\text{strain})$$

➤ If $\tau_R/T = D \ll 1$, stress = $\eta \frac{d}{dt}$ (strain)

$T \equiv$ dynamic
time scale

$$\Pi = -\eta \nabla \vec{v} \quad \underline{\text{viscous}}$$

➤ If $\tau_R/T = D \gg 1$, stress $\cong \frac{\eta}{\tau_R}$ (strain)

$$\sim E (\text{strain}) \quad \underline{\text{elastic}}$$

➤ Limit of “freezing-in”: $D \gg 1$ is criterion.

- $D \sim$ Deborah Number $\sim |\nabla V|/\omega_Z \sim \tau_{relax}/\tau_{dyn}$
- Limit for elasticity: $D \gg 1 \rightarrow$ limit for elasticity
- Why “Deborah”? \rightarrow

Hebrew Prophetess Deborah:

“The mountains flowed before the Lord.” (Judges)

∴

- Revisit Heraclitus (1500 years later):
“All things flow” – if you can wait long enough

Simulation Setup

- PIXIE2D: a DNS code solving 2D MHD equations in real space:

$$\partial_t A + \mathbf{v} \cdot \nabla A = \eta \nabla^2 A$$

$$\partial_t \omega + \mathbf{v} \cdot \nabla \omega = \frac{1}{\mu_0 \rho} \mathbf{B} \cdot \nabla \nabla^2 A + \nu \nabla^2 \omega + f$$

- 1024^2 resolution.
- External forcing f is isotropic homogeneous.
- Periodic boundary conditions (both).
- Initial conditions:

- (1) bimodal: $A_I(x, y) = A_0 \cos 2\pi x$

- (2) unimodal: $A_I(x, y) = A_0 * \begin{cases} -(x - 0.25)^3 & 0 \leq x < 1/2 \\ (x - 0.75)^3 & 1/2 \leq x < 1 \end{cases}$